REFERENCE NUMERALS LIST

1, 2, 3, 4	Robot
1.1, 2.1, 3.1, 4.1	Control
1.2, 2.2, 3.2, 4.2	Storage means
1.3, 2.3, 3.3, 4.3	Network card
1.3a, 2.3a, 3.3a, 4.3a	Input means
1.3b, 2.3b, 3.3b, 4.3b	Transmitting means
1.3c, 2.3c, 3.3c, 4.3c	Receiving means
1.4, 2.4, 3.4, 4.4	Microprocessor
1.4a, 2.4a, 3.4a, 4.4a	Processing means
1.4b, 2.4b, 3.4b, 4.4b	Decision means
1.5, 2.5, 3.5, 4.5	Driver means
5, 5'	Line
6	Hub
7	Operating device
S1-S15	Method step
j	Affirmed interrogation
n	Negated interrogation
L	"local" starting mode
R	"remote" starting mode

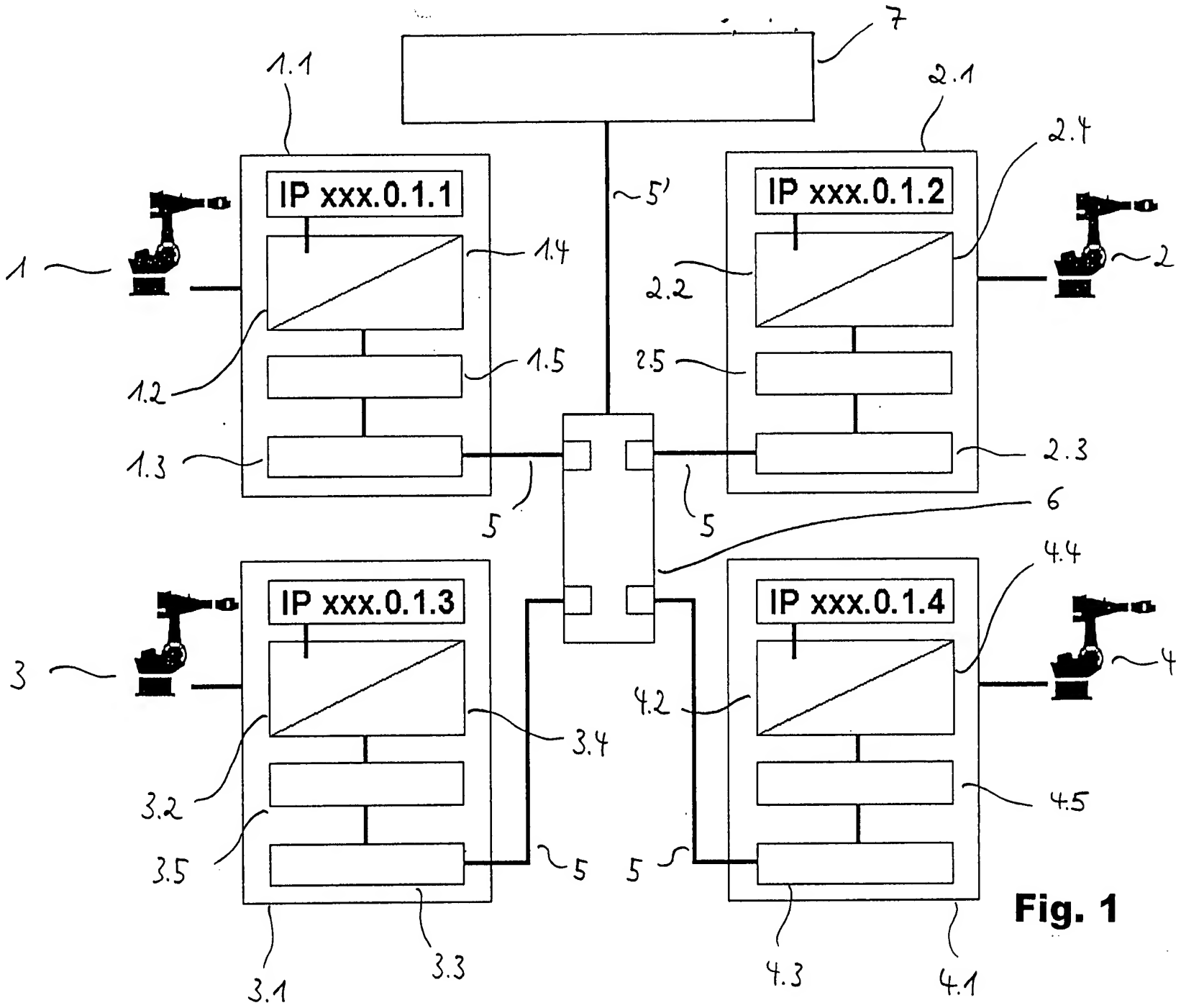
7
1.1
2.1
IP xxx.0.1.1
IP xxx.0.1.2
5'
2.4
1
2
1.4
2.2
1.2
1.5
2.5
1.3
2.3
5
5
6
IP xxx.0.1.3
IP xxx.0.1.4
4.4
3
4
4.2
3.4
3.2
4.5
3.5
5
5
3.1
3.3
4.3
4.1

Fig. 1

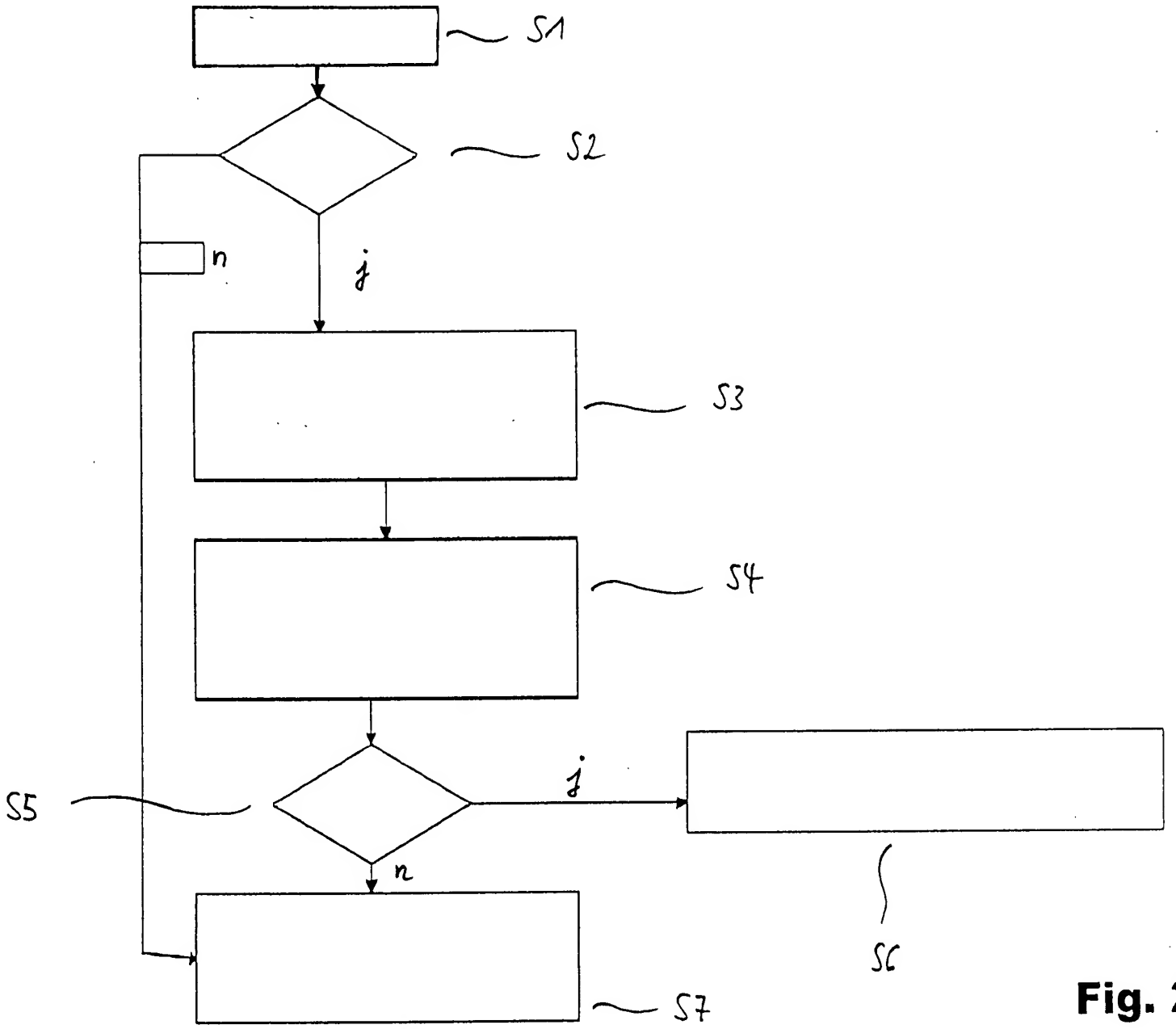

Fig. 2

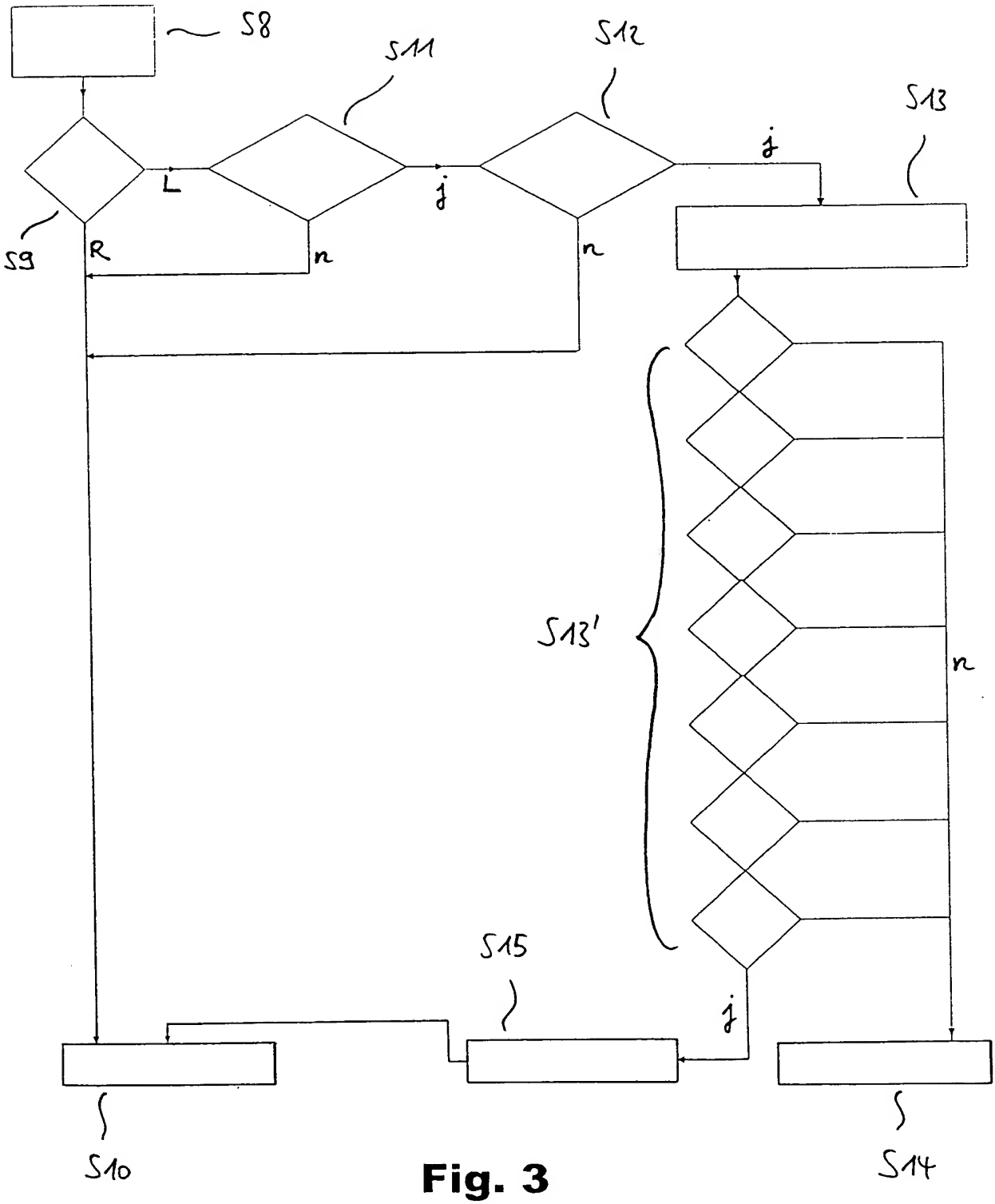

Fig. 3